



# S115 RUGGED SUBMERSIBLE STAND-ALONE LINEAR POSITION SENSOR

Position feedback for industrial and scientific applications

- **Non-contacting inductive technology to eliminate wear**
- **Travel set to customer's requirement**
- **Compact and self-contained**
- **High durability and reliability**
- **High accuracy and stability**
- **Sealing to IP68 10bar/IP69K**



As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek® has the expertise to supply a sensor to suit a wide variety of applications.

Our S115 is a heavy-duty version of the S114 sensor with a stronger 12.6mm push rod, recommended for applications where vibration is an issue or there is a need for longer travel sensors which are to be mounted horizontally between rod eyes. It remains an affordable, durable, high-accuracy position sensor designed for applications where the sensor would be completely submerged during normal operation. The unit is highly compact and space-efficient, being responsive along almost its entire length. Like all Positek® sensors, the S115 provides a linear output proportional to travel. Each sensor is supplied with the output calibrated to the travel required by the customer, any stroke from 0-5mm to 0-800mm and with full EMC protection built in. The sensor is very robust, the body and push rod being made of 316 stainless steel for long service life and environmental resistance. Overall performance, repeatability and stability are outstanding over a wide temperature range. The sensor is easy to install with mounting options including stainless steel M8 rod eye bearings and body clamps. The push rod can be supplied free or captive with female M8 thread, an M8 rod eye, dome end or magnetic tip. M12 and 1/2" rod eye option available. Captive push rods can be sprung loaded, in either direction, on sensors up to 300mm of travel. The S115 also offers a selection of mechanical and electrical options, environmental sealing is to IP68 10bar/IP69K.

## SPECIFICATION

### Dimensions

Body diameter	35 mm
Body length (Axial version)	calibrated travel + 168 mm
Body length (Radial version)	calibrated travel + 189 mm
Push rod extension	calibrated travel + 7 mm, OD 12.6 mm

*For full mechanical details see drawing S115-11*

<b>Independent Linearity</b>	$\leq \pm 0.25\%$ FSO @ 20°C - up to 450 mm
	$\leq \pm 0.5\%$ FSO @ 20°C - over 450 mm
	$\leq \pm 0.1\%$ FSO @ 20°C* available upon request.

\*Sensors with calibrated travel from 10 mm up to 400 mm.

### Temperature Coefficients

$< \pm 0.01\%/^{\circ}\text{C}$  Gain &  
 $< \pm 0.01\%$ FS/ $^{\circ}\text{C}$  Offset

### Frequency Response

$> 10$  kHz (-3dB)  
 $> 300$  Hz (-3dB) 2 wire 4 to 20 mA

### Resolution

Infinite

### Noise

$< 0.02\%$  FSO

### Environmental Temperature Limits (Non Icing)

Operating	-40°C to +125°C standard
	-20°C to +85°C buffered
Storage	-40°C to +125°C

### Sealing

IP68 10bar/IP69K

### EMC Performance

EN 61000-6-2, EN 61000-6-3

### Vibration

IEC 68-2-6: 10 g

### Shock

IEC 68-2-29: 40 g

### MTBF

350,000 hrs 40°C Gf

### Drawing List

S115-11

Sensor Outline

*Drawings, in AutoCAD® dwg or dxf format, available on request.*

**Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs - please contact us with your requirements.**

*For further information please contact:*

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S115-17g



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## How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

Our technology overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

We also offer a range of ATEX-qualified intrinsically-safe sensors.

## TABLE OF OPTIONS

**CALIBRATED TRAVEL:** Factory set to any length from 0-5mm to 0-800mm (e.g. 254mm)

### ELECTRICAL INTERFACE OPTIONS

OUTPUT SIGNAL	SUPPLY INPUT	OUTPUT LOAD
Standard: 0.5-4.5V dc ratiometric	+5V dc nom. $\pm$ 0.5V.	5k $\Omega$ min.
Buffered: 0.5-4.5V dc	+24V dc nom. + 9-28V.	5k $\Omega$ min.
$\pm$ 5V dc	$\pm$ 15V dc nom. $\pm$ 9-28V.	5k $\Omega$ min.
0.5-9.5V dc	+24V dc nom. + 13-28V.	5k $\Omega$ min.
$\pm$ 10V dc	$\pm$ 15 V dc nom. $\pm$ 13.5-28V.	5k $\Omega$ min.
Supply Current	10mA typical, 20mA maximum.	
4-20mA (2 wire)	+24 V dc nom. + 18-28V.	300 $\Omega$ @ 24V.
(3 wire sink)	+24 V dc nom. + 13-28V.	950 $\Omega$ @ 24V.
(3 wire source)	+24 V dc nom. + 13-28V.	300 $\Omega$ max.

### CONNECTOR/CABLE OPTIONS

Cable with Pg 7 gland Axial or Radial, IP68 10bar/IP69K  
Cable length >50 cm – please specify length in cm

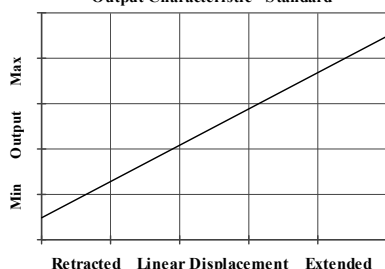
### MOUNTING OPTIONS

M8 rod eye bearing ( radial versions), Body Tube Clamp/s (axial or radial versions). M12 and 1/2" rod eye option available.

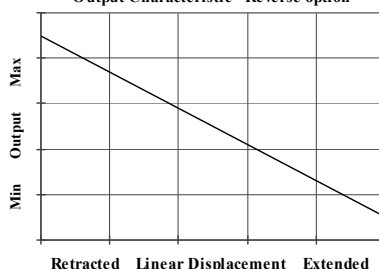
**PUSH ROD OPTIONS** – Retained<sup>†</sup> or Free with M8x1.25 female thread, M8 rod eye bearing or Magnetic tip, Spring loaded - retract or extend, Dome end<sup>#</sup>.

<sup>†</sup> standard, retained with female thread.  
<sup>#</sup> with spring extend.

Output Characteristic - Standard



Output Characteristic - Reverse option



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S115-17g

# S115 Rugged Submersible Stand-Alone Linear Position Sensor

	a	b	c	d	e	f	g	h	j
S115 .	Displacement	Output	Connections	Option	Option	Option	Option	Option	Z-code

a Displacement (mm)		Value
Displacement in mm	e.g. 0 - 254 mm	<b>254</b>
b Output		
Supply V dc V <sub>s</sub> (tolerance)	Output	Code
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	<b>A</b>
±15V nom. (±9 - 28V)	±5V	<b>B</b>
+24V nom. (13 - 28V)	0.5 - 9.5V	<b>C</b>
±15V nom. (±13.5 - 28V)	±10V	<b>D</b>
+24V nom. (18 - 28V)	4 - 20mA 2 wire	<b>E</b>
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	<b>F</b>
+24V nom. (9 - 28V)	0.5 - 4.5V	<b>G</b>
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	<b>H</b>
c Connections		Code
Cable Gland - Radial	IP68 10bar	<b>Ixx</b>
Cable Gland - Axial	IP68 10bar	<b>Lxx</b>
Specify required cable length 'xx' in cm. e.g. L2000 specifies cable gland with 20 m of cable, 50 cm supplied as standard.		
d Body Fittings		Code
None - default		blank
M8 Rod-eye Bearing	Radial body style only	<b>N</b>
e Body Clamps		Code
Body Clamps - 1 pair		<b>P</b>
Body Clamps - 2 pairs		<b>P2</b>
f Sprung Push Rod		Code
None - default		blank
Spring Extend	Up to 300mm displacement.	<b>R</b>
Spring Retract	Captive push rod only.	<b>S</b>
g Push Rod Fittings		Code
None - default	Female Thread M8x1.25x12 deep	blank
Dome end	Requires option 'R'	<b>T</b>
M8 Rod-eye Bearing		<b>U</b>
Magnetic Tip		<b>WA</b>
h Push Rod Options		Code
Captive - default	Push rod is retained	blank
Non-captive	Push rod can depart body	<b>V</b>
j Z-code		Code
≤± 0.1% @20°C Independent Linearity displacement between 10mm & 400mm only!		<b>Z650</b>
1/2" Rod eye options available		<b>Z825</b>
M12 Rod eye options available		<b>Z826</b>

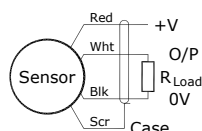


# Installation Information

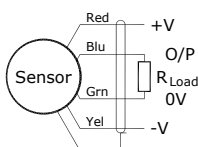
## S115 RUGGED SUBMERSIBLE STAND-ALONE LINEAR POSITION SENSOR

Output Option	Output Description:	Supply Voltage: $V_s$ (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	$\geq 5k\Omega$
B	$\pm 5V$	$\pm 15V$ nom. ( $\pm 9 - 28V$ )	$\geq 5k\Omega$
C	0.5 - 9.5V	+24V nom. (13 - 28V)	$\geq 5k\Omega$
D	$\pm 10V$	$\pm 15V$ nom. ( $\pm 13.5 - 28V$ )	$\geq 5k\Omega$
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	$\approx 0 - 300\Omega$ max. @24V $\sim 1.2$ to 6V across 300 $\Omega$ $\{R_L \text{ max.} = (V_s - 18) / 20^{-3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	$\approx 0 - 950\Omega$ max. @24V $\sim 3.8$ to 19V across 950 $\Omega$ $\{R_L \text{ max.} = (V_s - 5) / 20^{-3}\}$
G	0.5 - 4.5V	+24V nom. (9 - 28V)	$\geq 5k\Omega$
H	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	$\approx 0 - 300\Omega$ max. $\sim 1.2$ to 6V across 300 $\Omega$

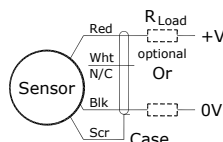
'A', 'C', 'G' & 'H'



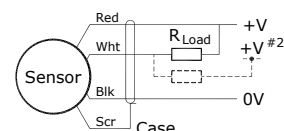
'B' & 'D'



'E'



'F'



$V_{\#2} = +5 - +28V$

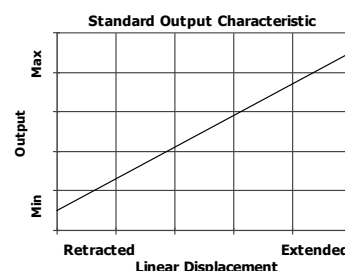
**Mechanical Mounting:** Depending on options; Body can be mounted by M8 rod eye or by clamping the sensor body - body clamps are available, if not already ordered. Target by M8x1.25 female thread or M8 rod eye. It is assumed that the sensor and target mounting points share a common earth.

Where the free end of the cable is to be terminated in a submerged position, adequate sealing must be provided to protect connections.

**Output Characteristic:** Target is extended 7 mm from end of body at start of normal travel. The output increases as the target extends from the sensor body, the calibrated stroke is between 5 mm and 800 mm.

### Incorrect Connection Protection levels:-

- A **Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.
- B & D Supply leads diode protected. Output must not be taken outside  $\pm 12V$ .
- C & G Supply leads diode protected. Output must not be taken outside 0 to 12V.
- E, F & H Protected against any misconnection within the rated voltage.



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